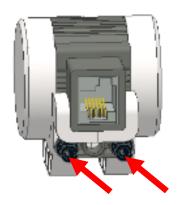
## QLB 2.1 Building Instructions



For more information on this and other educational robots go to: <a href="https://www.whillockvisions.com">www.whillockvisions.com</a>. Permission granted to make copies for classroom use.

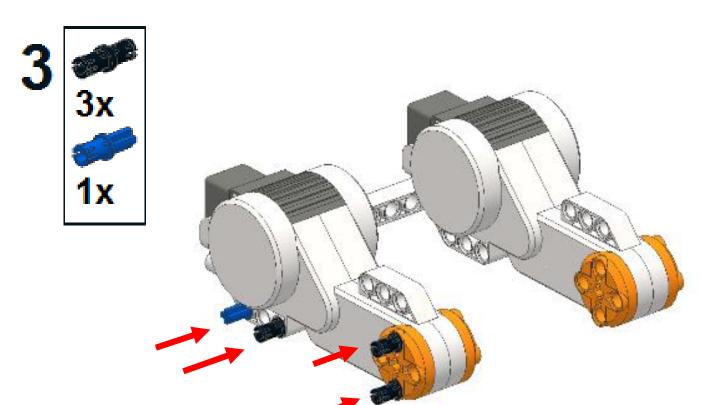
Email: RandWemail@gmail.com

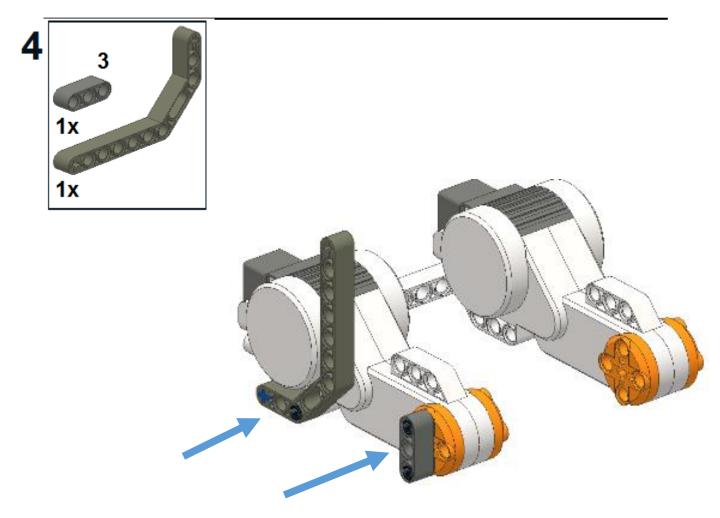




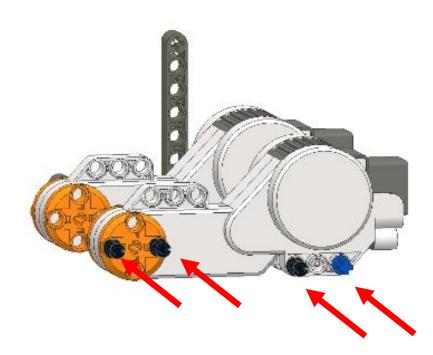


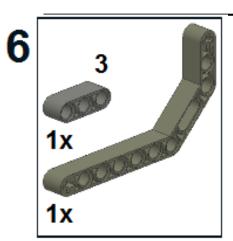


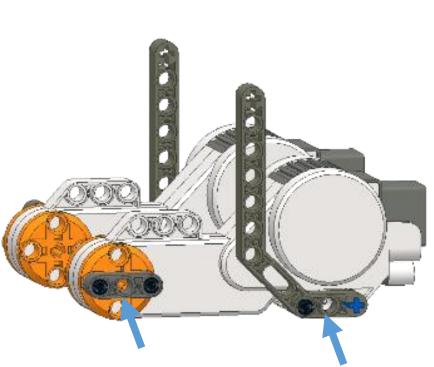


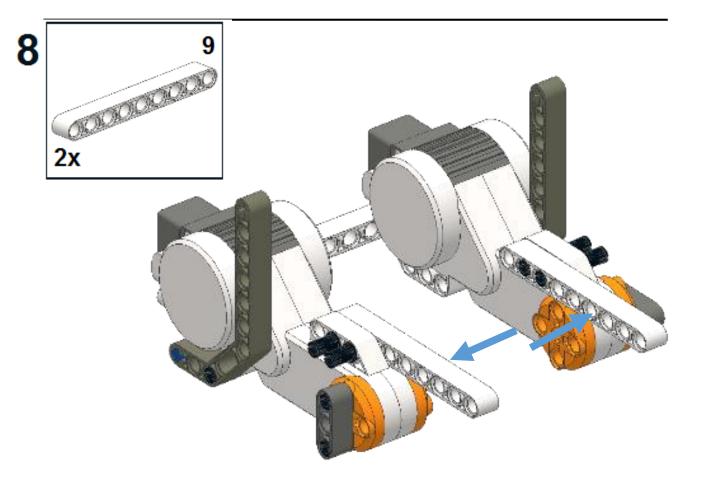


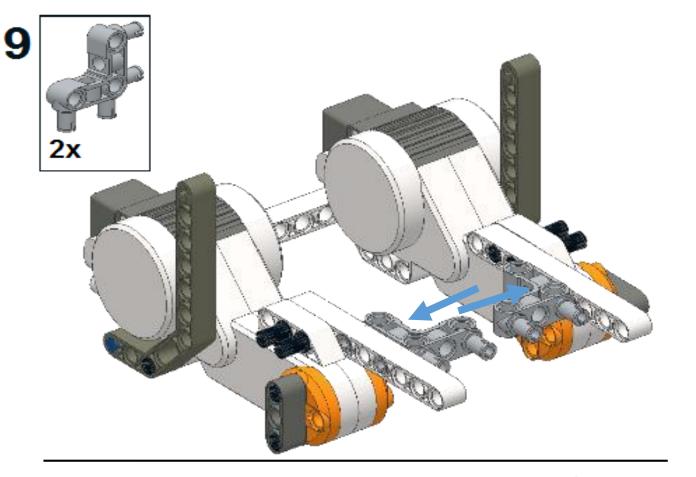


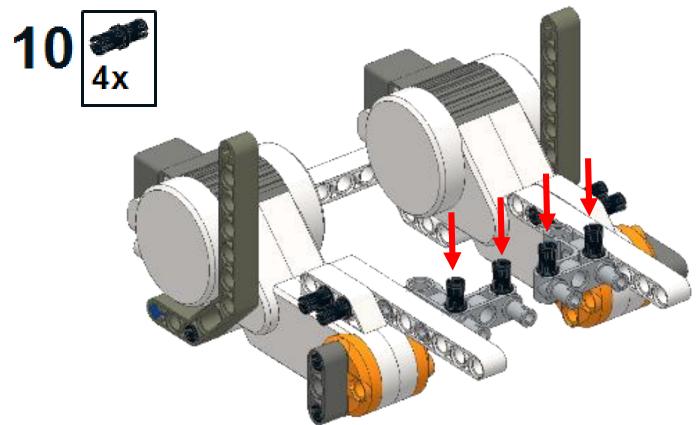


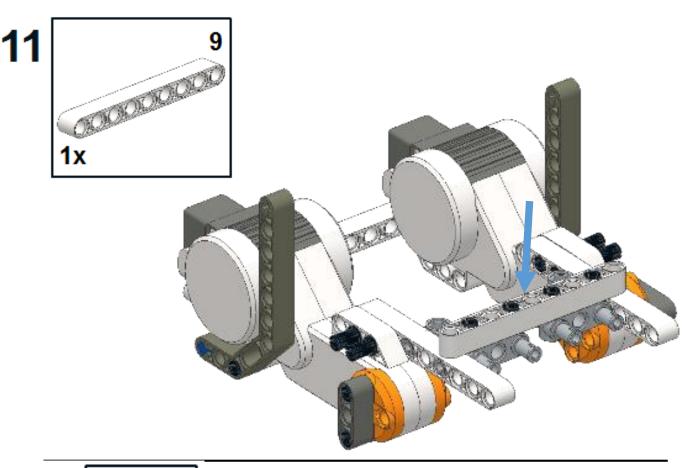


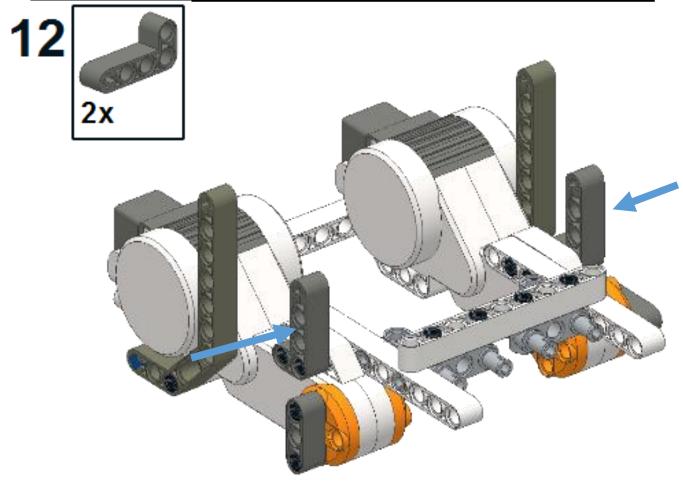


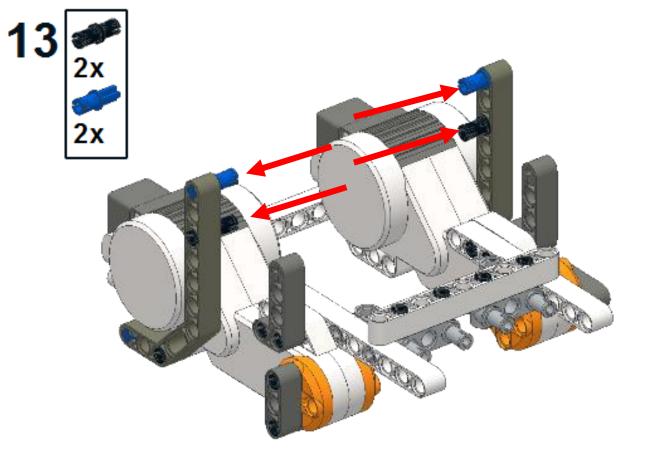


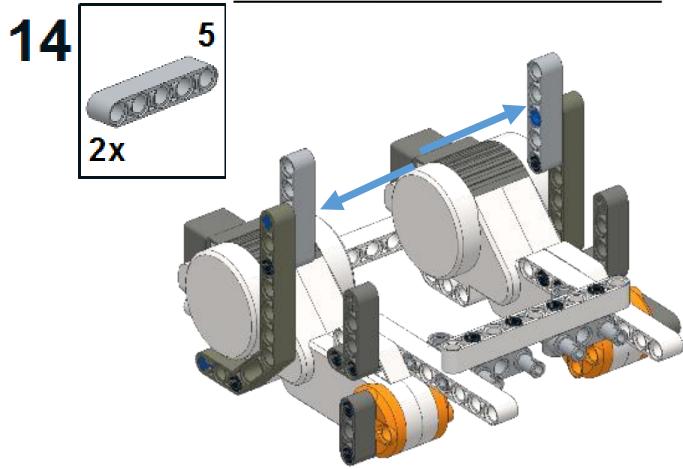


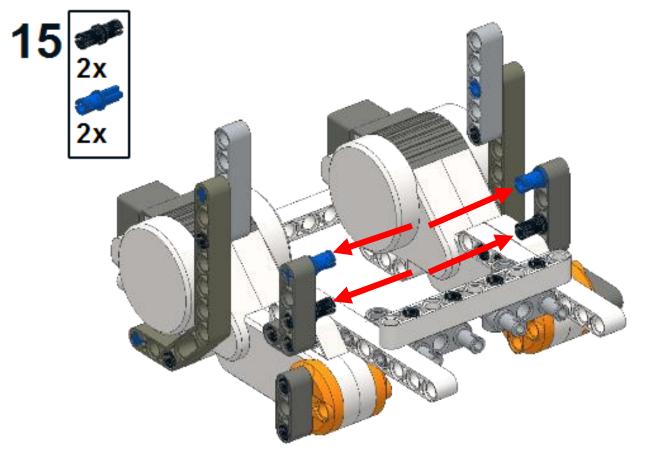


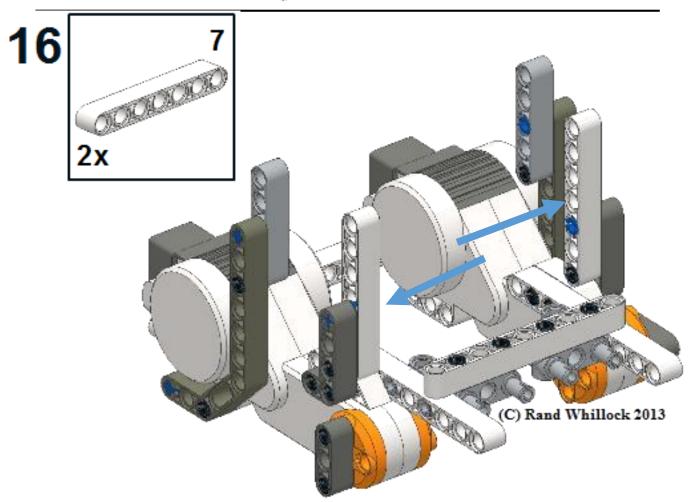


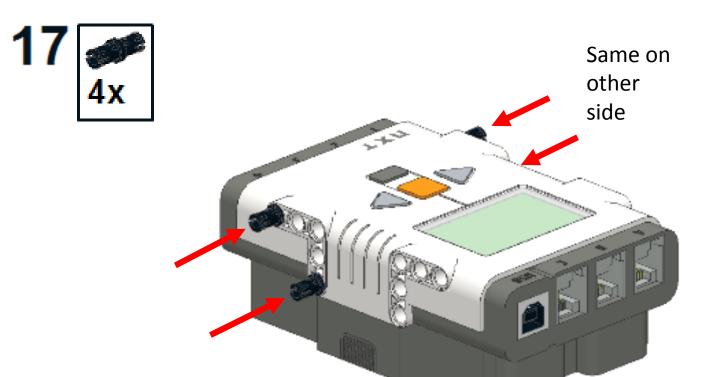


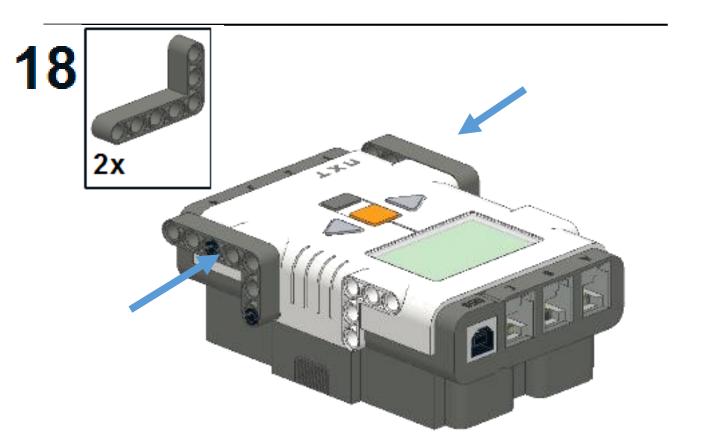


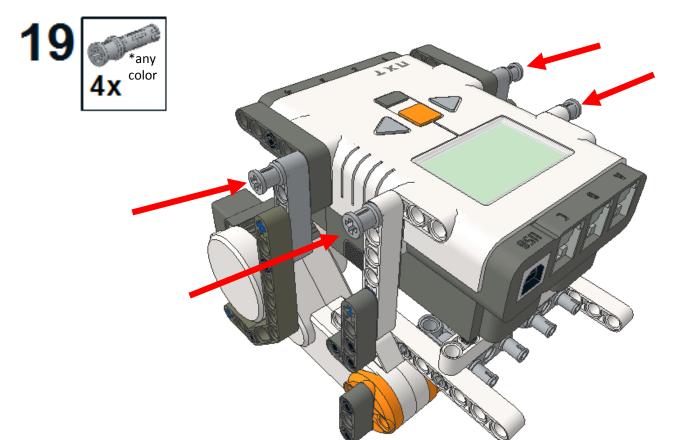


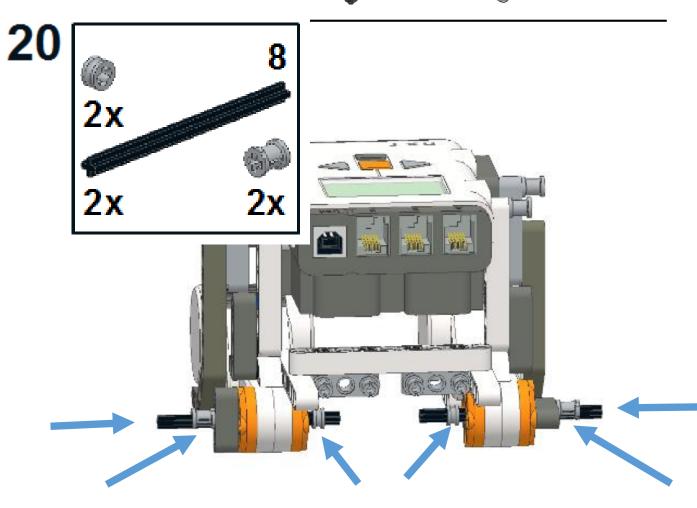


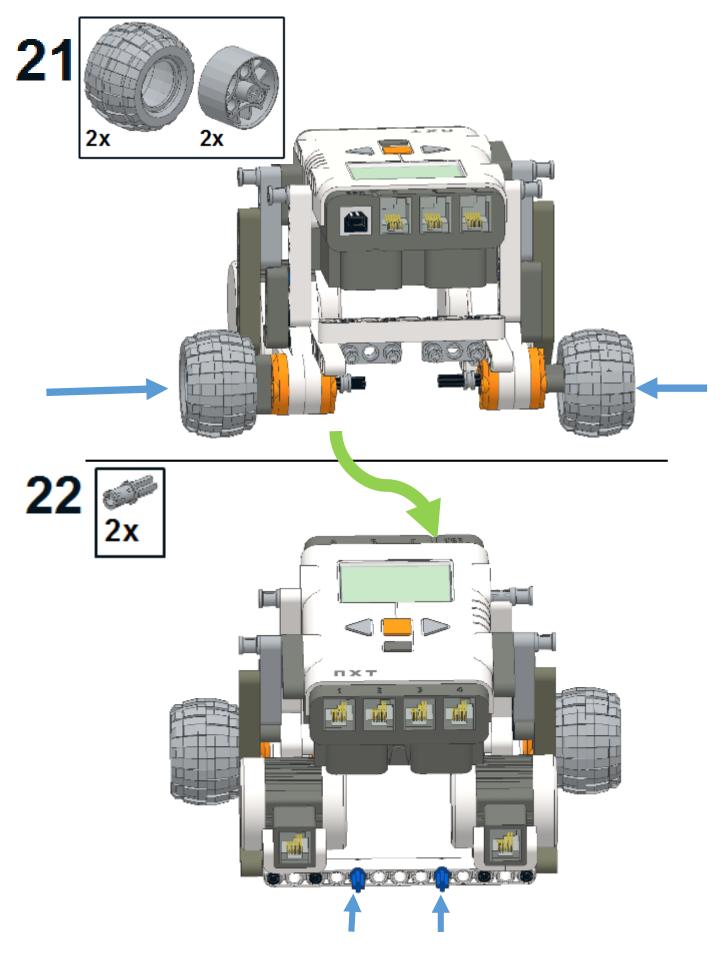


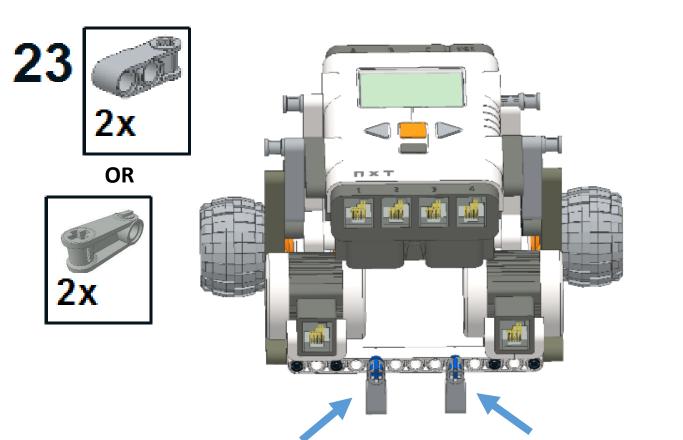


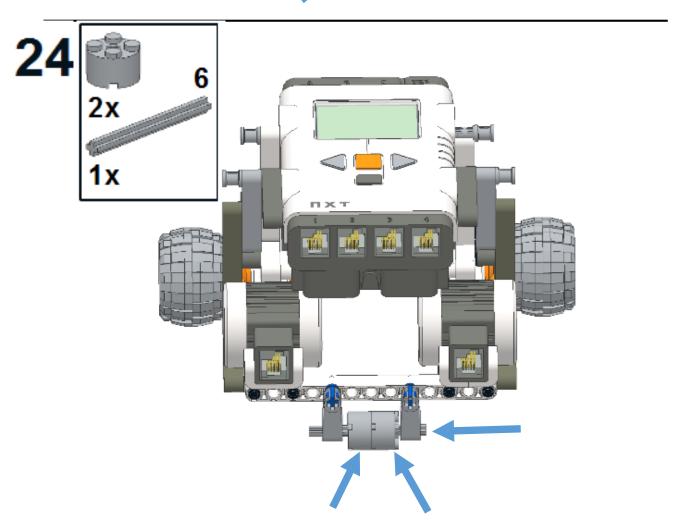


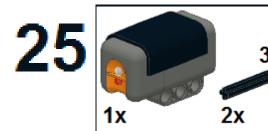


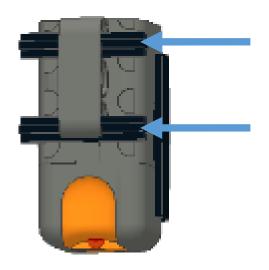


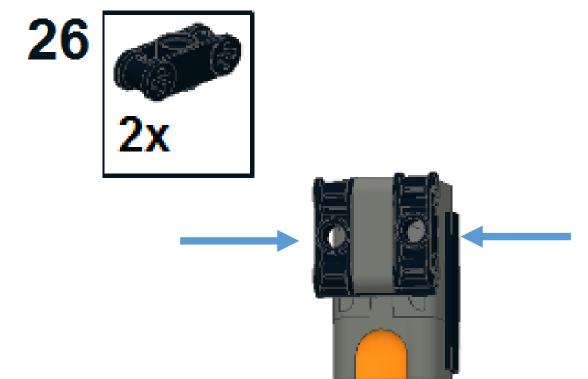




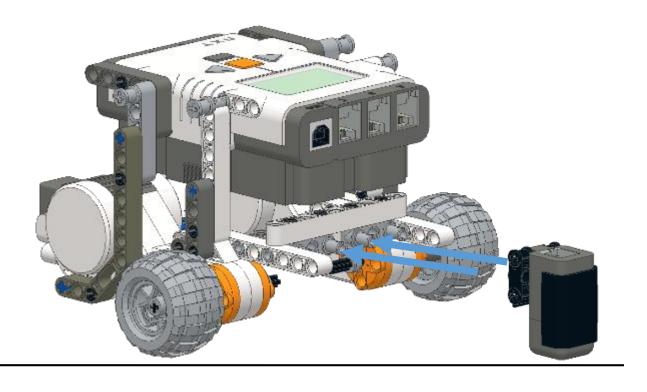




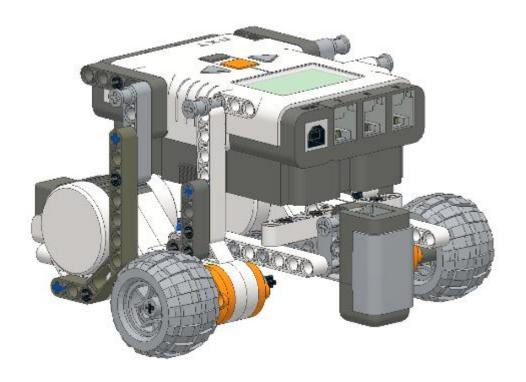




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Use wires to connect the left motor to output port B and the right motor to output port C. Connect the light sensor (if used) to input port 3.

Customize the robot to make it yours.

- Add a plow in front for pushing objects
- Change the size of the beams added in step
  8 to accommodate different attachments
- Add an arm
- Try different sized wheels
- Try different roller / caster options for rear wheels

## Part List

